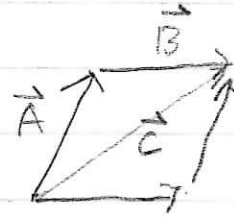


Basic properties of vector

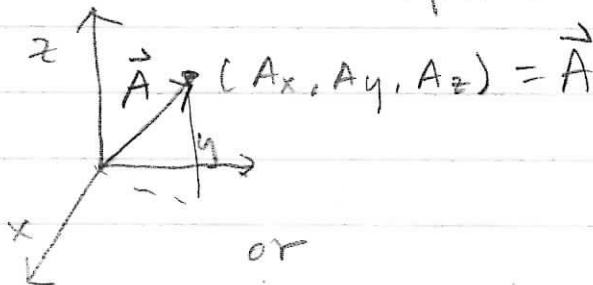
$$\vec{C} = \vec{A} + \vec{B} = \vec{B} + \vec{A}$$

$$a(\vec{A} + \vec{B}) = a\vec{A} + a\vec{B}$$

$$(a+b)\vec{A} = a\vec{A} + b\vec{A}$$



expression in ^{3D} coordinate system

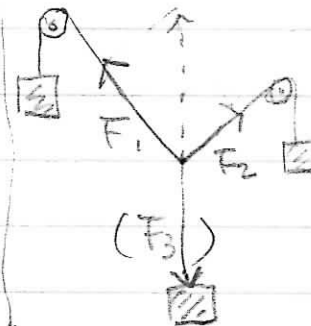


$$\vec{A} = \hat{i}A_x + \hat{j}A_y + \hat{k}A_z$$

$\hat{i}, \hat{j}, \hat{k}$ are orthonormal
unit vectors

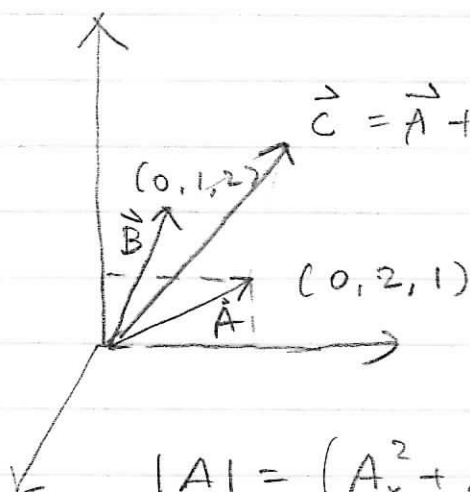
$$\begin{aligned}\vec{A} + \vec{B} &= (A_x, A_y, A_z) + (B_x, B_y, B_z) \\ &= (A_x + B_x, A_y + B_y, A_z + B_z)\end{aligned}$$

$$\vec{A} + \vec{B} = \hat{i}(A_x + B_x) + \hat{j}(A_y + B_y) + \hat{k}(A_z + B_z)$$



$$\vec{F}_1 + \vec{F}_2 + \vec{F}_3 = 0$$

$$\vec{F}_3 = -(\vec{F}_1 + \vec{F}_2)$$



$$\vec{C} = \vec{A} + \vec{B} = (0, 3, 3)$$

Benefit of coordinate
expression
(just add numbers!)

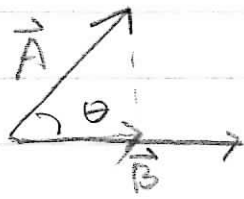
$$|\vec{A}| = (A_x^2 + A_y^2 + A_z^2)^{1/2} \quad \text{Pythagorean theorem.}$$

$$|\vec{C}| = (0 + 9 + 9)^{1/2} = \sqrt{18} = 3\sqrt{2}$$

Basic math

Vector 2

Dot product (내적) $\leftarrow$ 동일한 성분은
같이 빼는 것



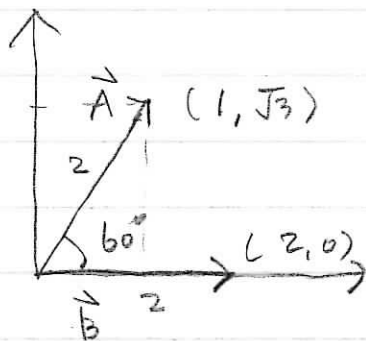
$$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta$$

In cartesian coordinate

$$(A_x, A_y, A_z) \cdot (B_x, B_y, B_z) = A_x B_x + A_y B_y + A_z B_z$$

$$\vec{i} \cdot \vec{i} = 1 ; \vec{i} \cdot \vec{j} = 0 ; \vec{i} \cdot \vec{k} = 0 ; \vec{j} \cdot \vec{k} = 0$$

$$(\vec{i} A_x + \vec{j} A_y + \vec{k} A_z) \cdot \vec{i} = A_x \quad \leftarrow \text{extract } \vec{i} \text{ component.}$$



$$\vec{A} \cdot \vec{B} = 2 \cdot 2 \cdot \cos 60^\circ = \underline{2}$$

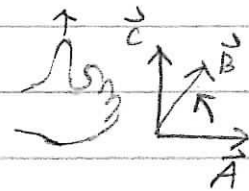
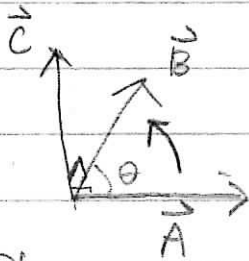
$$(2, 0) \cdot (1, \sqrt{3}) = 2 + 0 \cdot \sqrt{3} = \underline{2}$$

Cross product (2/7/7) 1/2

$$\vec{C} = \vec{A} \times \vec{B}$$

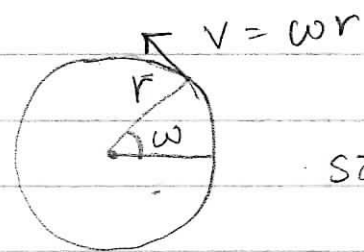
$$|\vec{C}| = |\vec{A}| \cdot |\vec{B}| \sin \theta, \quad \vec{C} \perp \vec{A}; \vec{C} \perp \vec{B}$$

(direction, right-handed system)



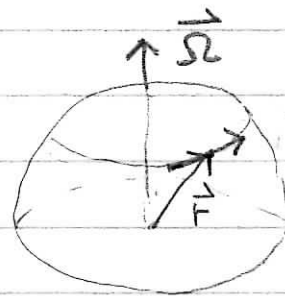
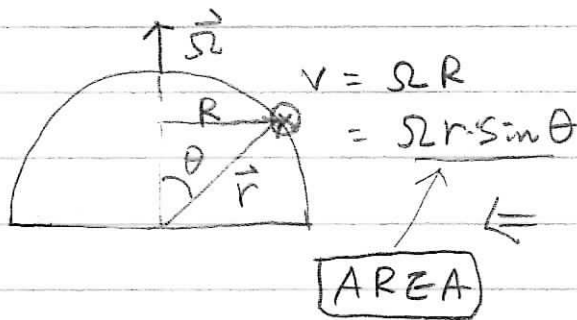
Physics

- Angular velocity
- Angular momentum
- Torque



Simple

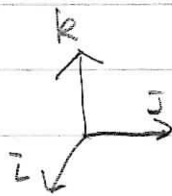
but reality



$$\vec{v} = \vec{\Omega} \otimes \vec{r} = \vec{\Omega} \times \vec{r}$$

can be generalized for any vector $\vec{r} \Rightarrow \vec{u} \dots$

Mathematics



$$\vec{i} \times \vec{j} = \vec{k}$$

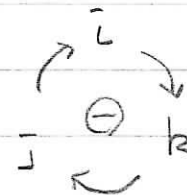
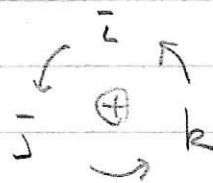
$$\vec{j} \times \vec{k} = \vec{i}$$

$$\vec{k} \times \vec{i} = \vec{j}$$

$$\vec{j} \times \vec{i} = -\vec{k}$$

$$\vec{k} \times \vec{j} = -\vec{i}$$

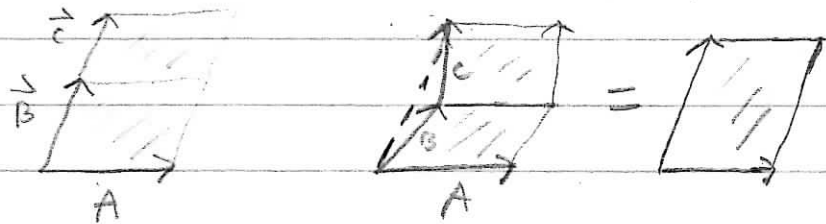
$$\vec{i} \times \vec{k} = -\vec{j}$$



Cross product (2/2) 2/2

Basic math
vector 4

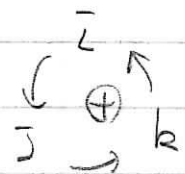
$$\vec{A} \times (\vec{B} + \vec{C}) = \vec{A} \times \vec{B} + \vec{A} \times \vec{C}$$



$$\begin{aligned}\vec{A} \times \vec{B} &= \vec{A} \times (\hat{i}B_x + \hat{j}B_y + \hat{k}B_z) \\ &= (\hat{i}A_x + \hat{j}A_y + \hat{k}A_z) \times \hat{i}B_x \\ &\quad + (\hat{i}A_x + \hat{j}A_y + \hat{k}A_z) \times \hat{j}B_y \\ &\quad + (\hat{i}A_x + \hat{j}A_y + \hat{k}A_z) \times \hat{k}B_z\end{aligned}$$

$$\begin{aligned}&= \hat{j} \times \hat{k} (-A_z B_y + A_y B_z) \\ &\quad + \hat{k} \times \hat{i} (A_z B_x - A_x B_z) \\ &\quad + \hat{i} \times \hat{j} (-A_y B_x + A_x B_y)\end{aligned}$$

$$\begin{aligned}\vec{A} \times \vec{B} &= \hat{i} (A_y B_z - A_z B_y) \\ &\quad + \hat{j} (A_z B_x - A_x B_z) \\ &\quad + \hat{k} (A_x B_y - A_y B_x)\end{aligned}$$



Del operator

del operator 1

Total variation of a function $F(x(t), y(t), z(t))$
during small time δt

$$\frac{dF}{dt} = \underbrace{\frac{\partial F}{\partial x} \frac{dx}{dt}}_u + \underbrace{\frac{\partial F}{\partial y} \frac{dy}{dt}}_v + \underbrace{\frac{\partial F}{\partial z} \frac{dz}{dt}}_w$$

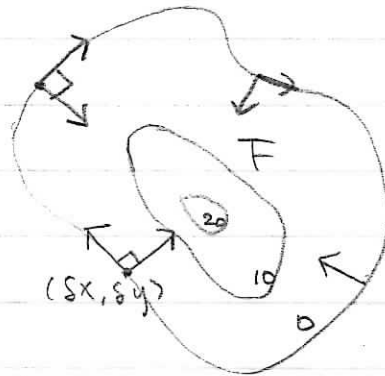
$$= \left(\hat{i} \frac{\partial F}{\partial x} + \hat{j} \frac{\partial F}{\partial y} + \hat{k} \frac{\partial F}{\partial z} \right) \cdot (\hat{i}u + \hat{j}v + \hat{k}w)$$

$$= \nabla F \cdot \vec{V}$$

$$\boxed{\nabla \equiv \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z}}$$

Gradient ∇F

$$\delta F = \frac{\partial F}{\partial x} \delta x + \frac{\partial F}{\partial y} \delta y$$



$$\left(\hat{i} \frac{\partial F}{\partial x} + \hat{j} \frac{\partial F}{\partial y} \right) \cdot (\hat{i} \delta x + \hat{j} \delta y) = 0$$

" ∇F is always orthogonal to a constant contour line.
& pointing to the direction obtaining maximum increase in F "

Basic math
del operator 2

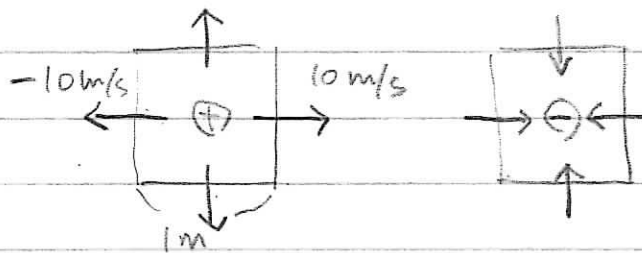
Divergence. $\nabla \cdot \vec{V}$

$$\left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot (u, v, w)$$

$$= \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}$$

A physical interpretation

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{V}) = 0$$

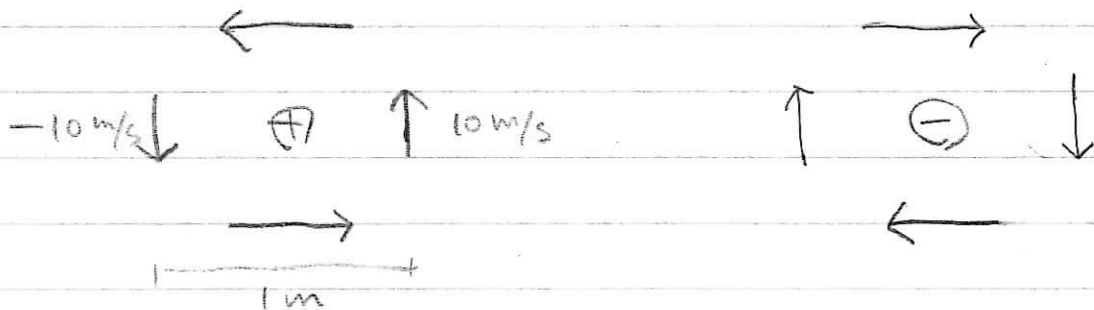


$$\frac{10 \text{ m/s} - (-10 \text{ m/s})}{1 \text{ m}} = 20 \text{ s}^{-1}$$

Curl $\nabla \times \vec{V}$

$$\left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \times (\hat{i}u + \hat{j}v + \hat{k}w)$$

$$= \hat{i} \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z} \right) + \hat{j} \left(\frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right) + \hat{k} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$$

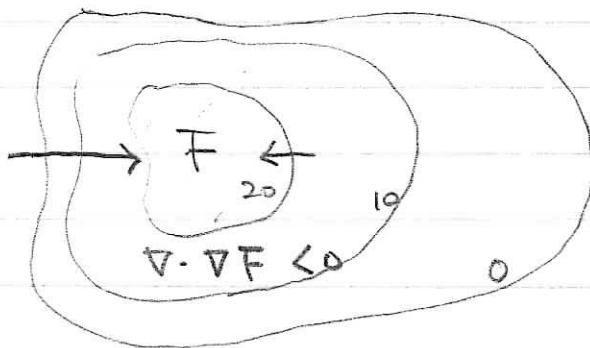


$$\frac{10 \text{ m/s} - (-10 \text{ m/s})}{1 \text{ m}} = 20 \text{ s}^{-1}$$

Basic math del operator 3

Laplacian $\nabla^2 F (= \nabla \cdot \nabla F)$
 $\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) F$

physically diffusion



lose a physical value
 (F; e.g. Temperature, wind speed)
 from the maximum region
 e.g.) diffusion equation.

$$\frac{\partial T}{\partial t} = c \nabla^2 T$$

